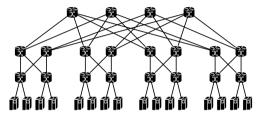
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Matthias Rost Technische Universität Berlin wissenschaftliche Aussprache, 25. März 2019

# Cloud Applications



#### Physical Infrastructure: Data Center

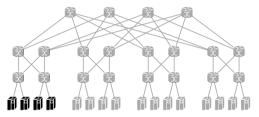


## Virtual Machines





## Physical Infrastructure: Data Center







# Virtual Machines





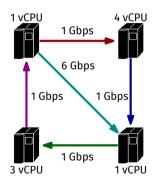




## Network-dependent Applications



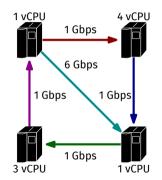
#### Virtual Network



## Network-dependent Applications



#### Virtual Network



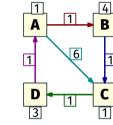
#### Goal: Predictable Performance

#### Network-dependent Applications

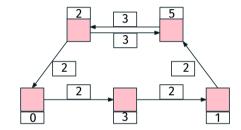


#### Request Virtual Network

#### Substrate Physical Network



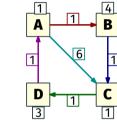
demand



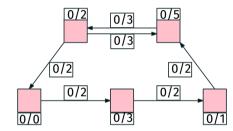
capacity

#### Request Virtual Network

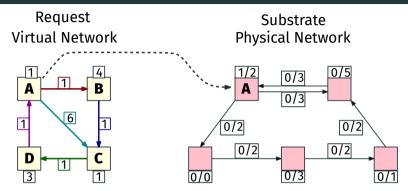
#### Substrate Physical Network



demand



used/total capacity

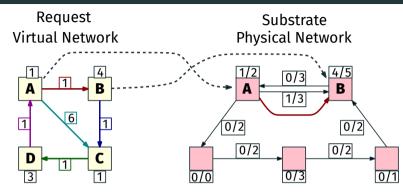


used/total capacity

#### demand

# Mapping Properties

virtual nodes are mapped to substrate nodes

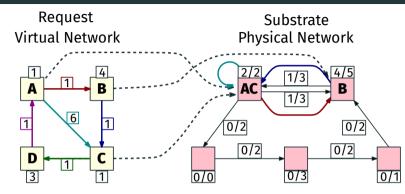


demand

## Mapping Properties

- virtual nodes are mapped to substrate nodes
- virtual edges are mapped to substrate paths

used/total capacity

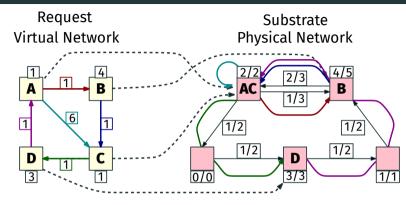


demand

used/total capacity

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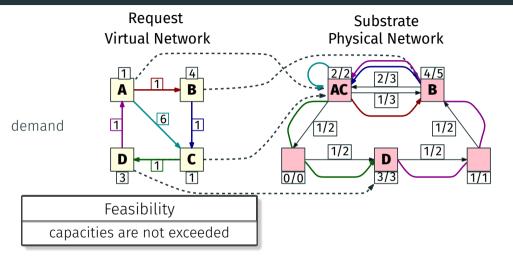


demand

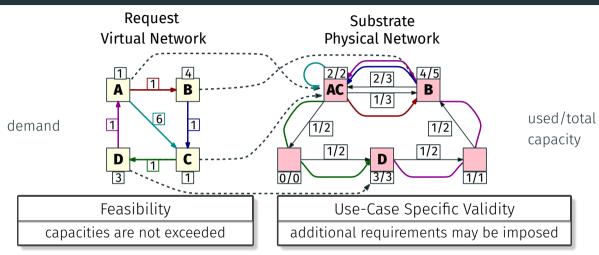
# Mapping Properties

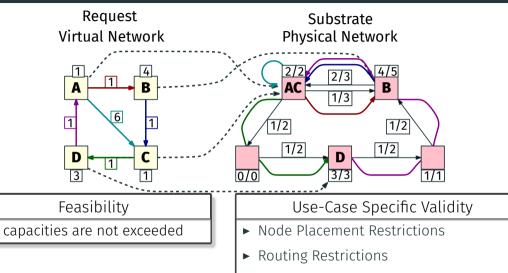
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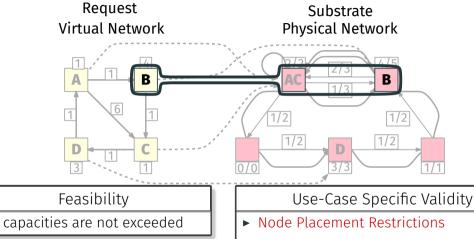


used/total capacity

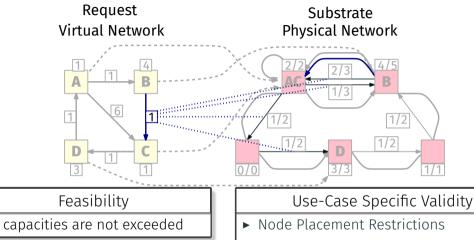




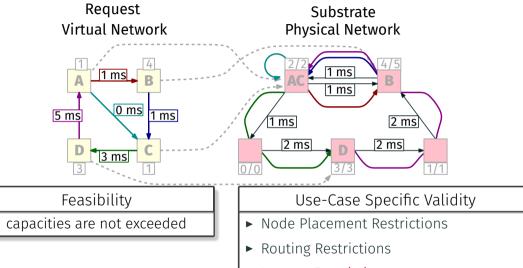
► Latency Restrictions



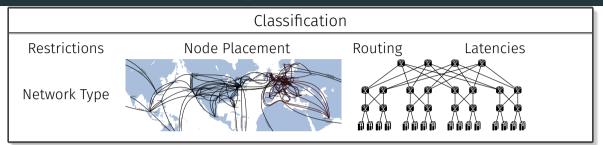
- Routing Restrictions
- Latency Restrictions

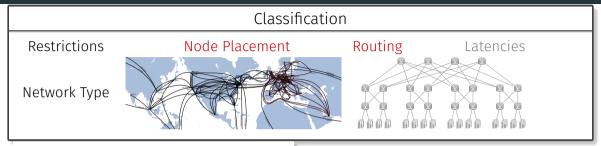


- Routing Restrictions
- ► Latency Restrictions



Latency Restrictions

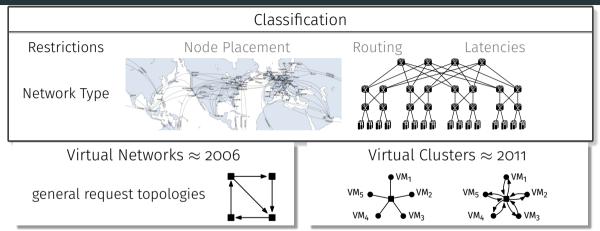


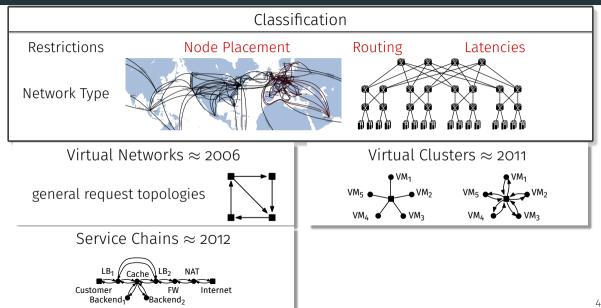


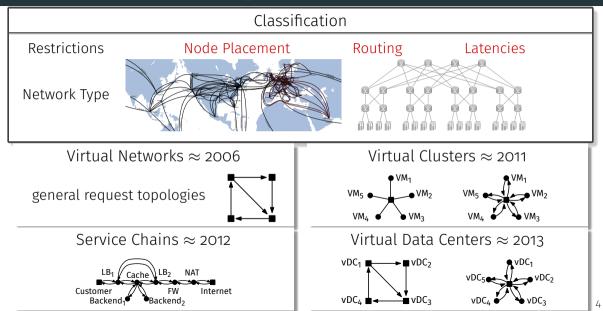
Virtual Networks  $\approx$  2006

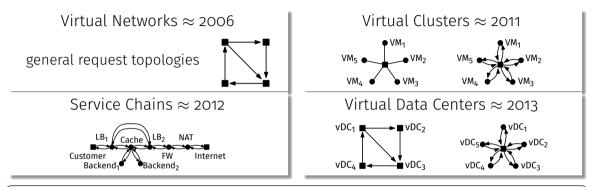
general request topologies

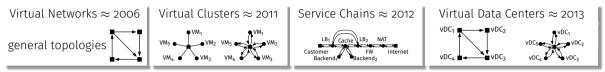












Finding 'good' embeddings is the core algorithmic challenge.

# Objectives

...

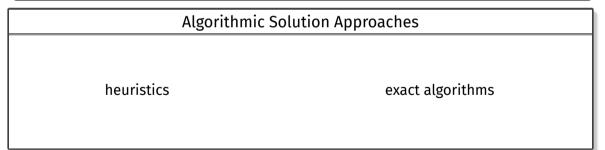
Online Setting - Request Sequence

- min. resource usage / costs
- ▶ min. resource fragmentation

Offline Setting – Multiple Requests

- max. profit via admission control
- min. resource consumption

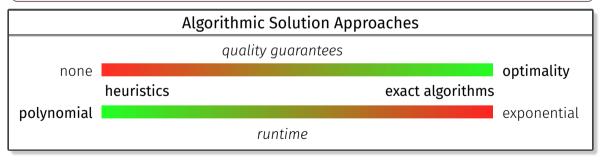




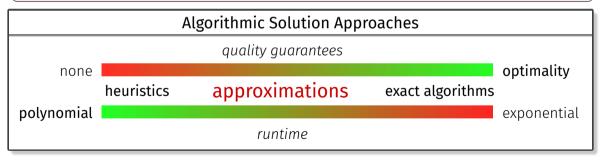




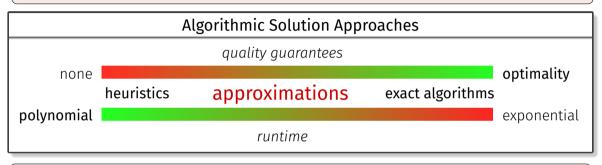






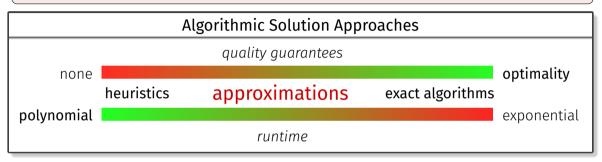


Finding 'good' embeddings is the core algorithmic challenge.



quality guarantees + bounded runtime  $\rightsquigarrow$  predictable algorithm performance

Finding 'good' embeddings is the core algorithmic challenge.



quality guarantees + bounded runtime  $\rightsquigarrow$  predictable algorithm performance

Until now: only heuristics and exact algorithms known.

Thesis Overview

# **Thesis Overview**

Prime Goals

1. Development of *efficient* approximation algorithms.

Virtual Network Embedding Problem

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1. Development of *efficient* approximation algorithms.

#### Virtual Network Embedding Problem

#### Computational Complexity

 Study structural hardness and inapproximability.

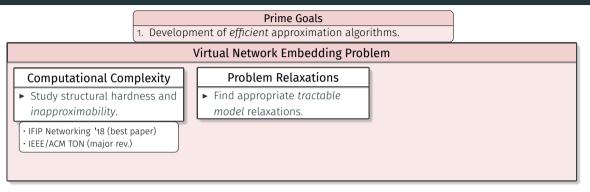
#### Prime Goals

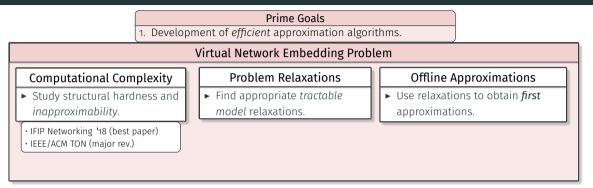
1. Development of *efficient* approximation algorithms.

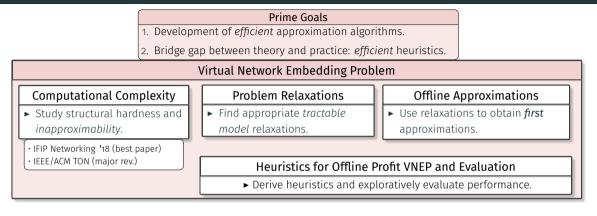
#### Virtual Network Embedding Problem

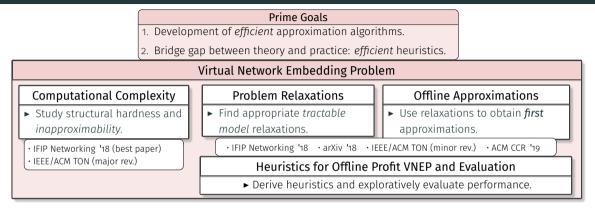
#### **Computational Complexity**

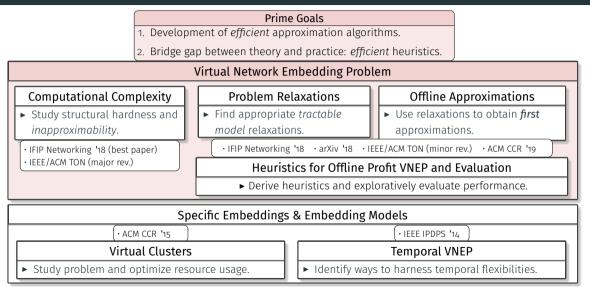
- Study structural hardness and inapproximability.
- IFIP Networking '18 (best paper)
- IEEE/ACM TON (major rev.)









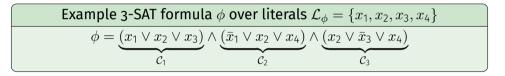


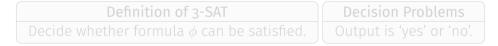
Computational Complexity of the VNEP

## Reminder: 3-SAT and $\mathcal{NP}$ -Completeness

#### 3-SAT-Formula $\phi$

 $\phi = \bigwedge_{\mathcal{C}_i \in \mathcal{C}_{\phi}} \mathcal{C}_i$  with  $\mathcal{C}_i \in \mathcal{C}_{\phi}$  being disjunctions of at most 3 literals.





Theorem: Karp [1972]3-SAT is  $\mathcal{NP}$ -complete.

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Example 3-SAT formula 
$$\phi$$
 over literals  $\mathcal{L}_{\phi} = \{x_1, x_2, x_3, x_4\}$   

$$\phi = \underbrace{(x_1 \lor x_2 \lor x_3)}_{\mathcal{C}_1} \land \underbrace{(\bar{x}_1 \lor x_2 \lor x_4)}_{\mathcal{C}_2} \land \underbrace{(x_2 \lor \bar{x}_3 \lor x_4)}_{\mathcal{C}_3}$$

Definition of 3-SATDecision ProblemsDecide whether formula  $\phi$  can be satisfied.Output is 'yes' or 'no'.

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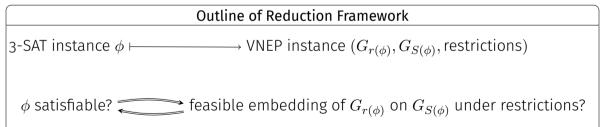
Theorem: Karp [1972]3-SAT is  $\mathcal{NP}$ -complete.

## Methodology: Proving $\mathcal{NP}$ -completeness

Proving  $\mathcal{NP}$ -completeness of the VNEP

1. Show that VNEP lies in  $\mathcal{NP}(\checkmark)$ .

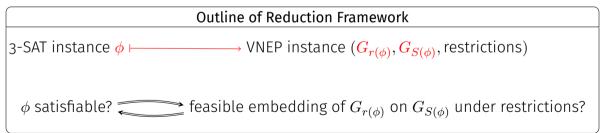
2. Reduce 3-SAT to VNEP.

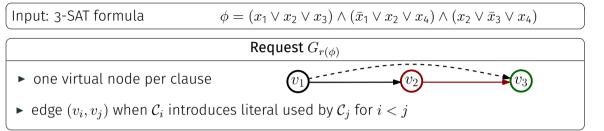


Proving  $\mathcal{NP}$ -completeness of the VNEP

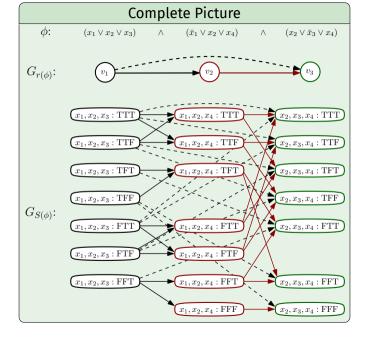
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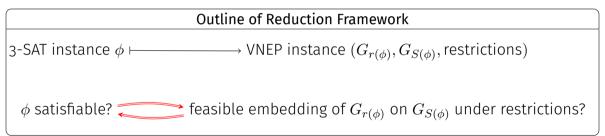
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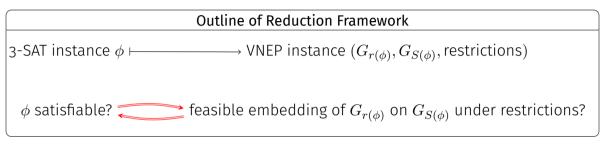




# Substrate G<sub>S(φ)</sub> 7 substrate nodes per clause: represent satisfying assignments edges as for request, only when assignments agree x<sub>1</sub>, x<sub>2</sub>, x<sub>3</sub> :TTT x<sub>1</sub>, x<sub>2</sub>, x<sub>3</sub> :TTT







#### Base Lemma

Formula  $\phi$  is satisfiable **if and only if** there exists a mapping of  $G_{r(\phi)}$  on  $G_{S(\phi)}$ , s.t.

(1) each virtual node  $v_i$  is mapped to a (satisfying) substrate node of the *i*-th clause, and

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Theorem: Decision VNEP is  $\mathcal{NP}$ -complete under node placement and routing restrictionsProof: via application of base lemma.

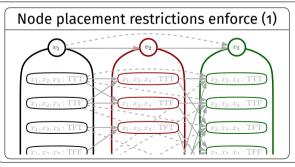
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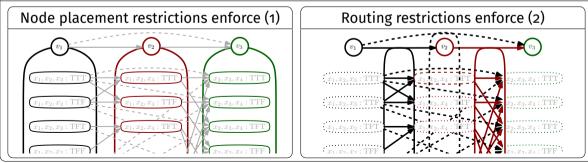
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# What about other restrictions?

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Theorem: VNEP is $\mathcal{NP}\text{-}complete$ under					
Node Restrictions		Edge Restrictions			
capacities	&	capacities			
capacities	&	routing			
placement	&	capacities			
placement	&	routing			
placement	&	latencies			

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Theorem: VNEP is $\mathcal{NP}$ -complete under			Theorem: $\mathcal{NP}\text{-}Completeness$ remains if
Node Restrictions Edge Restrictions			substrate is acyclic <b>and</b>
capacities	&	capacities	request is acyclic <b>and</b>
capacities	&	routing	request is planar <b>and</b>
placement	&	capacities	request has max degree 12.
placement	&	routing	
placement	&	latencies	

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...

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- ► Finding a feasible embedding is in general not possible in polynomial-time<sup>a</sup>.
- ▶ The VNEP is *inapproximable* under any objective even for a single request<sup>a</sup>.
- Computing valid mappings is already hard!

<sup>*a*</sup>unless  $\mathcal{P} = \mathcal{N}\mathcal{P}$  holds

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## Additional Inapproximability Results

- ► Intractability even for *approximate* solutions when relaxing either
  - node capacities or latencies by factor  $2 \varepsilon$ , or
  - edge capacities by factor  $\log n / \log \log n$ , with n = number of substrate nodes <sup>a</sup>.

<sup>*a*</sup>unless  $\mathcal{NP} \subseteq \mathcal{BP}$ -TIME $(\bigcup_{d \ge 1} n^{d \log \log n})$ 

## **Problem Relaxations**

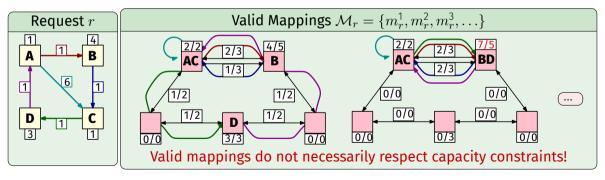
VNEP is $\mathcal{NP}$ -complete under			
Node Restrictions Edge Restrictions			
÷	&	÷	
placement	&	routing	
placement	&	latencies	

VNEP is $\mathcal{NP}$ -complete under			
Node Restrictions Edge Restrictions			
÷	&	:	
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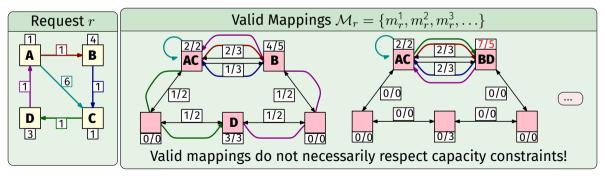
Validity restrictions are non-negotiable.

VNEP is $\mathcal{NP}$ -complete under	Focus
Node Restrictions Edge Restrictions	Computing valid mappings under node
placement & routing	placement and routing restrictions.

VNEP is $\mathcal{NP}$ -complete under	Focus
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Valid Mapping Problem (VMP)	Focus
Find valid mapping $m_r \in \mathcal{M}_r$ of least cost:	Computing valid mappings under node
$c_S(m_r) = \sum_{x \in G_S} c_S(x) \cdot A(m_r, x)$	placement and routing restrictions.



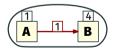
## Solving the Valid Mapping Problem: DYNVMP Intuition

DYNVMP algorithm: solve VMP via dynamic programming.

## Solving the Valid Mapping Problem: DYNVMP Intuition

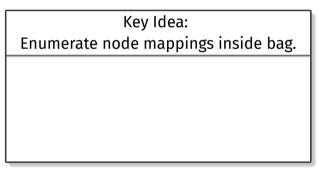
DYNVMP algorithm: solve VMP via dynamic programming.

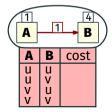
Start with simplest request: single edge.



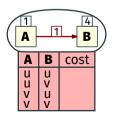
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DYNVMP algorithm: solve VMP via dynamic programming.



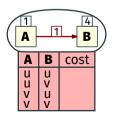


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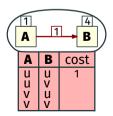
# Key Idea: Enumerate node mappings inside bag. Validity ► nodes: trivial ► edges: graph-search

DYNVMP algorithm: solve VMP via dynamic programming.



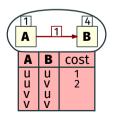
# Key Idea:Enumerate node mappings inside bag.ValidityMapping Costs• nodes: trivial• nodes: trivial• edges:<br/>graph-search• edges: shortest-paths<br/>(using allowed edges)

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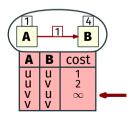
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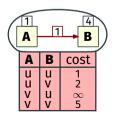
DYNVMP algorithm: solve VMP via dynamic programming.



# Key Idea: Enumerate node mappings inside bag. Validitv

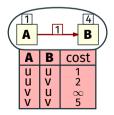
- nodes: trivial
- edges: graph-search
- Mapping Costs
- ▶ nodes: trivial
- ► edges: shortest-paths (using allowed edges)

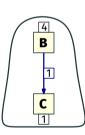
DYNVMP algorithm: solve VMP via dynamic programming.



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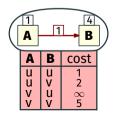
Enumerate node mappings inside bag.

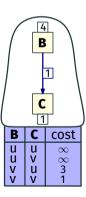
# Validity

# **Mapping Costs**

- nodes: trivial 🔹 ト nodes: trivial
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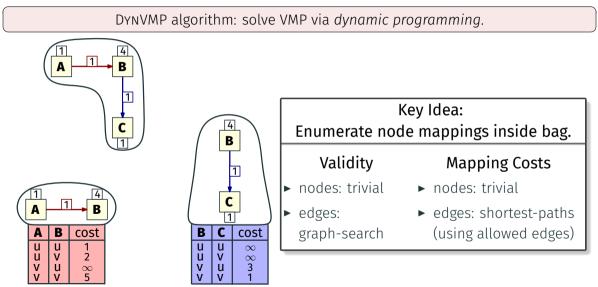
# Validity

graph-search

► edges:

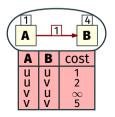
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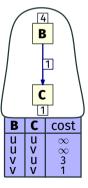
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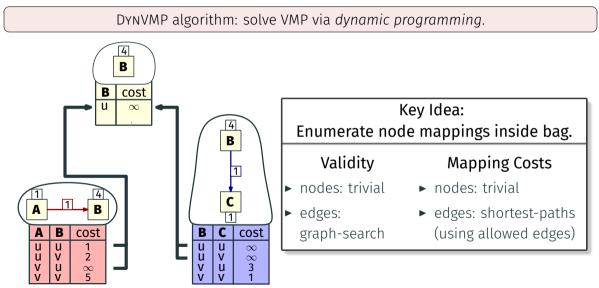
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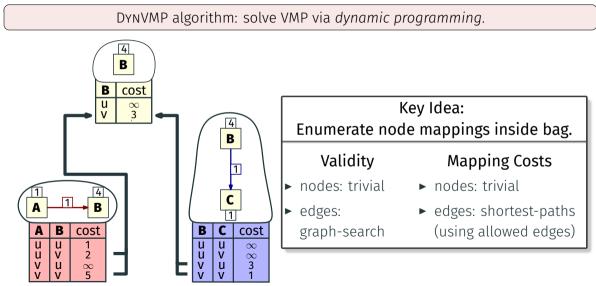
graph-search

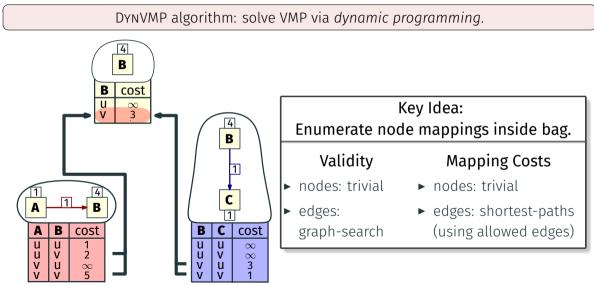
► edges:

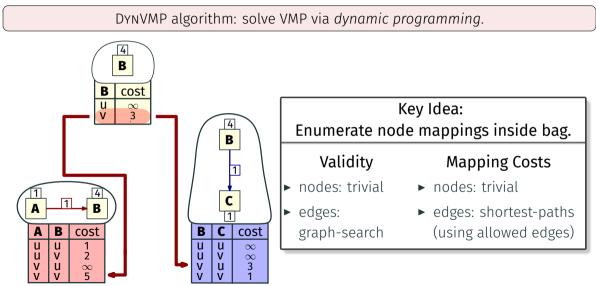
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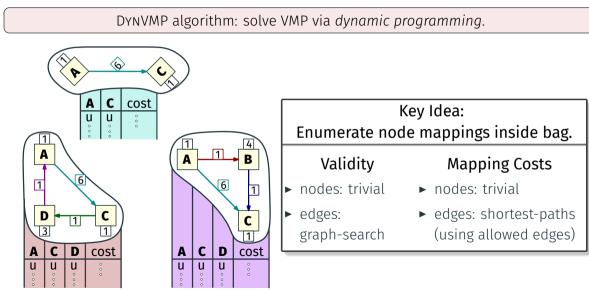
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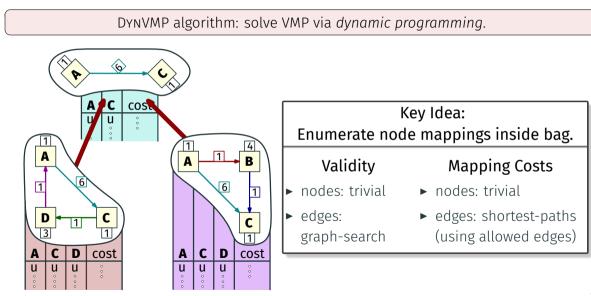




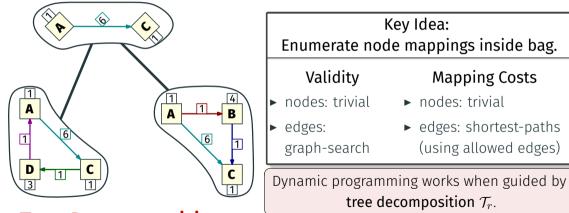




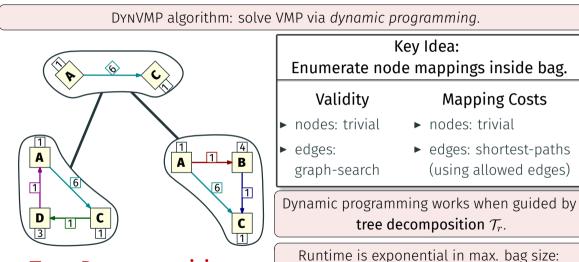




#### DYNVMP algorithm: solve VMP via dynamic programming.



Tree Decomposition



Tree Decomposition

the **treewidth** tw( $\mathcal{T}_r$ ).

#### Excursion: Tree Decompositions and Treewidth

• Important concept in theoretical computer science  $\rightarrow$  parametrized complexity theory

► Finding tree decomposition of minimal width is *NP*-hard but *fixed-parameter tractable*.

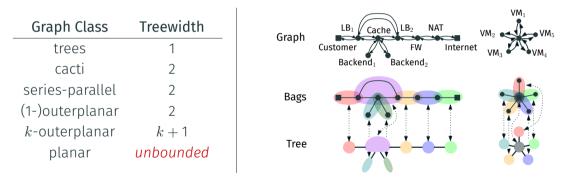
#### Excursion: Tree Decompositions and Treewidth

- Important concept in theoretical computer science  $\rightarrow$  parametrized complexity theory
- ► Finding tree decomposition of minimal width is *NP*-hard but *fixed-parameter tractable*.

Graph Class	Treewidth	
trees	1	
cacti	2	
series-parallel	2	
(1-)outerplanar	2	
<i>k</i> -outerplanar	k + 1	
planar	unbounded	

#### Excursion: Tree Decompositions and Treewidth

- Important concept in theoretical computer science  $\rightarrow$  parametrized complexity theory
- ► Finding tree decomposition of minimal width is *NP*-hard but *fixed-parameter tractable*.



Important request topologies have small treewidth.

#### Theorem: Correctness & Runtime - Node Placement & Routing

DYNVMP solves the VMP in **XP**-time  $\mathcal{O}(|V_r|^3 \cdot |V_S|^{2 \cdot \text{tw}(\mathcal{T}_r)+3})$ .

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Theorem:	Generalization	– Node Placement & Routing & Latencies
The	DYNVMP algorithm finds	a $(1 + \varepsilon_{LCSP})$ -optimal valid mapping, if one exists.
The	<b>XP-</b> runtime is bounded	by $\mathcal{O}( V_r ^2 \cdot ( V_r  \cdot  V_S ^{2 \cdot \operatorname{tw}(\mathcal{T}_r) + 2} + \operatorname{time}_{LCSP}(\varepsilon_{LCSP}))).$

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## Important Observation

- ► The VNEP reduces to the VMP, when any valid mapping is also feasible.
- ► DYNVMP solves the *online VNEP* **optimally / approximatively** in this setting.

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## Important Observation

- ► The VNEP reduces to the VMP, when any valid mapping is also feasible.
- ► DYNVMP solves the *online VNEP* **optimally / approximatively** in this setting.

# Key Application: Solving the *Fractional* Offline VNEP

#### Solving the Fractional Offline VNEP

Offline VNEP – request set $\mathcal{R} = \{r_1, r_2, \ldots\}$		
Profit Variant	Cost Variant	
▶ Profit for requests $b_r > 0$	• Resource costs $c_S: G_S \to \mathbb{R}_{\geq 0}$	
► Task: Embed subset of requests ► Task: Find <i>feasible</i> embeddings for all		
feasibly maximizing the attained profit.	requests minimizing cost.	

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feasibly maximizing the attained profit.	requests minimizing cost.	

Fractional Offline VNEP: Linear Program (LP) for Profit			
► Selection of <i>k</i> -th mapping:	$f_r^k \in [0, 1]$	$\forall r \in \mathcal{R}, m_r^k \in$	$\mathcal{M}_r$ (1)
Select at most 'one' mapping:	$\sum f_r^k \leq 1$	$\forall r \in \mathcal{R}$	(2)
Enforce capacities:	$\sum_{r \in \mathcal{R}} \sum_{m_r^k \in \mathcal{M}_r} A(m_r^k, x) \cdot f_r^k \le d_S(x)$	$\forall x \in G_S$	(3)
Maximize the profit:	$\max \sum_{r \in \mathcal{R}} \sum_{m_r \in \mathcal{M}_r} b_r \cdot f_r^k$		(4)

## Solving the Fractional Offline VNEP

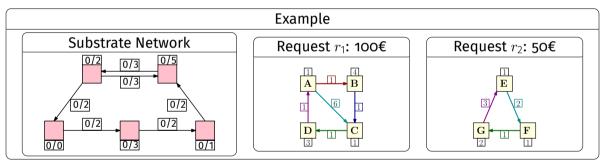
Fractional Offline VNEP: Linear Program (LP) for Profit			
► Selection of <i>k</i> -th mapping:	$f_r^k \in [0, 1]$	$\forall r \in \mathcal{R}, m_r^k \in \mathcal{J}$	$\mathcal{M}_r$ (1)
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<ul> <li>Maximize the profit:</li> </ul>	$\max \sum_{r \in \mathcal{R}} \sum_{m_r^k \in \mathcal{M}_r} b_r \cdot f_r^k$		(4)

#### XP-Tractable via Column Generation

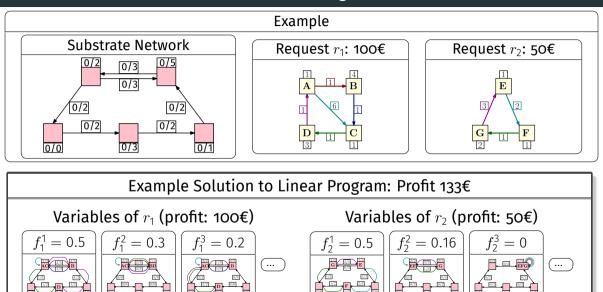
- Dual LP has finitely many variables but exponential number of constraints.
- ► Dual constraints can be separated using DYNVMP algorithm.  $\rightsquigarrow$  runtime  $\mathcal{O}\left(\operatorname{poly}\left(\sum_{r \in \mathcal{R}} |V_r|^3 \cdot |V_S|^{2 \cdot \operatorname{tw}(\mathcal{T}_r) + 3}\right)\right)$  due to Grötschel et al. [1988]

Offline Approximation Algorithms

## Randomized Rounding: Intuition

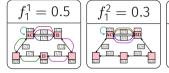


## Randomized Rounding: Intuition



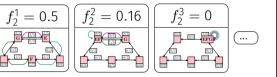
Example Solution to Linear Program: Profit 133€

# Variables of $r_1$ (profit: 100€)





## Variables of $r_2$ (profit: 50€)



Idea: Treat weights as probabilities!

Algorithm: RoundingProcedure

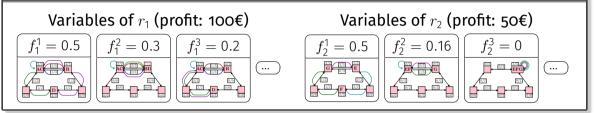
Input : LP solution

```
foreach r \in \mathcal{R} do
```

```
choose m_r^k with probability f_r^k
```

end

Example Solution to Linear Program: Profit 133€



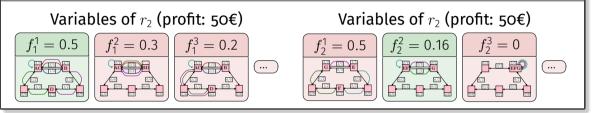
Idea: Treat weights as probabilities!
Algorithm: RoundingProcedure
Input : LP solution
foreach $r \in \mathcal{R}$ do
choose $m_r^k$ with probability $f_r^k$

#### **Rounding Outcomes**

Iter. Req. 1 Req. 2 Profit max Load

end

#### Example Solution to Linear Program: Profit 133€



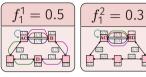
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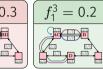
#### Rounding Outcomes

Iter.	Req. 1	Req. 2	Profit	max Load
1	$m_1^1$	$m_2^2$	150€	200%

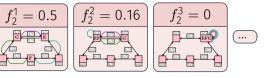
#### Example Solution to Linear Program: Profit 133€

#### Variables of request 1







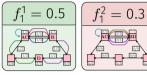


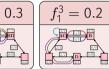
Idea: Treat weights as probabilities!	
Algorithm: RoundingProcedure	I
Input : LP solution	
foreach $r \in \mathcal{R}$ do	
$ $ choose $m_r^k$ with probability $f_r^k$	
end	

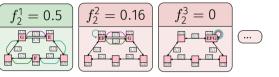
Rounding Outcomes										
lter.	lter. Req. 1 Req. 2 Profit max Load									
1	$m_1^1$	$m^2_2$	150€	200%						
2	$m_1^3$	Ø	100€	100%						

#### Example Solution to Linear Program: Profit 133€

#### Variables of request 1



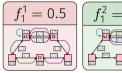




Idea: Treat weights as probabilities!	Rounding Outcomes				
Algorithm: RoundingProcedure	Iter.	Req. 1	Req. 2	Profit	max Load
Input : LP solution	1	$m_1^1$	$m^2_2$	150€	200%
foreach $r \in \mathcal{R}$ do	2	$m_1^3$	Ø	100€	100%
choose $m_r^k$ with probability $f_r^k$	3	$m_1^1$	$m_2^1$	150€	200%
end					

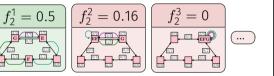
### Example Solution to Linear Program: Profit 133€

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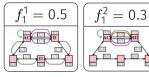


Idea: Treat weights as probabilities!	Rounding Outcomes				
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choose $m_r^k$ with probability $f_r^k$	3	$m_1^1$	$m^{1}_{2}$	150€	200%
end	4	$m_1^2$	$m_2^1$	150€	200%

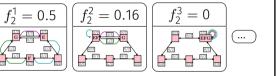
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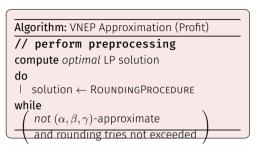
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choose $m_r^k$ with probability $f_r^k$	3	$m_1^1$	$m^1_2$	150€	200%	
end	4	$m_1^2$	$m^1_2$	150€	200%	
	:	:	:	:	:	



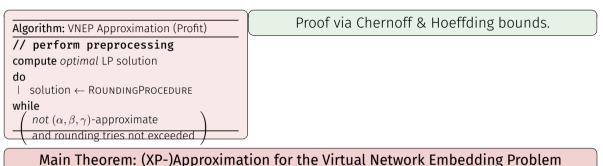
Algorithm: RoundingProcedure

Input : LP solution

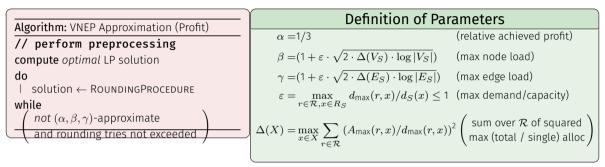
foreach  $r \in \mathcal{R}$  do

```
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```

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The Algorithm returns  $(\alpha, \beta, \gamma)$ -approximate solutions of at least an  $\alpha$  fraction of the optimal profit, and allocations on nodes and edges within factors of  $\beta$  and  $\gamma$  of the original capacities, respectively, with high probability.



**Main Theorem: (XP-)Approximation for the Virtual Network Embedding Problem** The Algorithm returns  $(\alpha, \beta, \gamma)$ -approximate solutions of at least an  $\alpha$  fraction of the optimal profit, and allocations on nodes and edges within factors of  $\beta$  and  $\gamma$  of the original capacities, respectively, with high probability.

Algorithm: VNEP Approximation (Profit)	Definition of Pa	rameters
// perform preprocessing	$\alpha = 1/3$	(relative achieved profit)
compute optimal LP solution	$\beta = (1 + \varepsilon \cdot \sqrt{2 \cdot \Delta(V_S) \cdot \log  V_S })$	(max node load)
do	$\gamma = (1 + \varepsilon \cdot \sqrt{2 \cdot \Delta(E_S) \cdot \log  E_S })$	(max edge load)
∣ solution ← ROUNDINGPROCEDURE while	$arepsilon = \max_{r \in \mathcal{R}, x \in R_S} d_{\max}(r, x) / d_S(x) \leq 1$	(max demand/capacity)
$(not (\alpha, \beta, \gamma) - approximate)$	$\Delta(X) = \max_{x \in X} \sum_{r \in \mathcal{R}} (A_{\max}(r, x) / d_{\max}(r, x))$	

#### Worst-Case Analysis

 $\beta \in \mathcal{O}(\varepsilon \cdot \max_{r \in \mathcal{R}} |V_r| \cdot \sqrt{|\mathcal{R}| \cdot \log |V_S|}) \qquad \gamma \in \mathcal{O}(\varepsilon \cdot \max_{r \in \mathcal{R}} |E_r| \cdot \sqrt{|\mathcal{R}| \cdot \log |E_S|})$ 

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Overview of XP-Approximation Results									
Obj.	Setting	Approximation Factors $\alpha \qquad \beta - \beta' \qquad \gamma - \gamma'$		ors $\gamma - \gamma'$	Runtime				
	$\langle \mathbf{VE}   \mathbf{NR} \rangle$	<u>α</u>	$\frac{\beta - \beta}{2}$	$\frac{\gamma - \gamma}{2}$	$\operatorname{poly}\left(\sum_{r\in\mathcal{R}} V_r ^3\cdot V_S ^{2\cdot\operatorname{tw}(\mathcal{T}_r)+3} ight)$				
Cost	$\langle \mathbf{VE}   \mathbf{NRL} \rangle$	$2 + 2 \cdot \varepsilon_{\text{LCSP}}$	$2 + 2 \cdot \varepsilon_{\text{LCSP}}$	$2 + 2 \cdot \varepsilon_{\text{LCSP}}$	$poly\left(\sum_{r\in\mathcal{R}} V_r ^2\cdot\left( V_r \cdot V_S ^{2\cdot\mathrm{tw}(\mathcal{T}_r)+2}+time_{LCSP}(\varepsilon_{LCSP})\right)\right)$				
Profit	$\langle  \mathbf{VE}     \mathbf{NR}  \rangle$	1/3	1	1	poly $\left(\sum_{r\in\mathcal{R}} V_r ^3\cdot V_S ^{2\cdot ext{tw}(\mathcal{T}_r)+3} ight)$				
	$\langle  \mathbf{VE}     \mathbf{NRL}  \rangle$	$1/(3 + 3 \cdot \varepsilon_{LCSP})$	$1 + \varepsilon_{LCSP}$	$1 + \varepsilon_{LCSP}$	$poly\left(\sum_{r\in\mathcal{R}} V_r ^2\cdot\left( V_r \cdot V_S ^{2\cdottw(\mathcal{T}_r)+2}+time_{LCSP}(\varepsilon_{LCSP}) ight) ight)$				
$ \beta' = \varepsilon \cdot \sqrt{2 \cdot \Delta(V_S) \cdot \log  V_S }, \ \gamma' = \varepsilon \cdot \sqrt{2 \cdot \Delta(V_S) \cdot \log  V_S } $									

•  $\varepsilon_{LCSP} > 0$  must hold; time<sub>LCSP</sub>( $\varepsilon_{LCSP}$ ) is polynomial in  $1/\varepsilon_{LCSP}$  (and input)

**Derived Heuristics & Evaluation** 

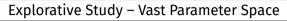
Derived Heuristics: Key Ideas

- ► Goal: feasibility
  - ► **reactive**: discard rounded mapping upon violation
  - proactive: forbid mappings violating capacities and recompute LP
- ► Sample solutions
- Different request orders

Benchmark Heuristics: WINE / VINE

- VINE single request mapping
  - ► uses randomized rounding to map virtual nodes
  - ► realizes edges via shortest paths
- ► WINE offline adaptation
  - greedy: process according to profit

#### Computational Evaluation: Setup



**Treewidth:** 1, 2, 3, 4

Number of requests: 40, 60, 80, 100

Node-Resource Factor (NRF): 0.2, 0.4, 0.6, 0.8, 1.0

Edge-Resource Factor (ERF): 0.25, 0.5, 1.0, 2.0, 4.0

Instances per combination: 15

Substrate: GEANT

#### Requests

- #nodes uniformly chosen from  $\{5, \ldots, 15\}$
- ► topology: random but with specific treewidth
- node mappings restricted to 10 nodes

Code available:

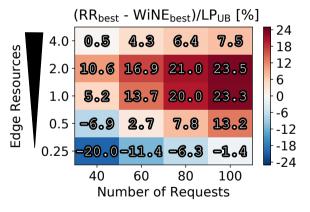
https://github.com/vnep-approx/

Investigate qualitative potential of randomized rounding heuristics.

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(RR <sub>best</sub> - WiNE <sub>best</sub> )/LP <sub>UB</sub> [%]									
S	4.0-	0.5	4.3	6.4	7.5	-24 -18			
Edge Resources	2.0-	10.6	16.9	21.0	23.5	- 12 - 6			
	1.0-	5.2	13.7	20.0	23.3	- 0			
dge	0.5	-6.9	2.7	7.8	13.2	6 12			
Щ	0.25	-20.0	-11.4	-6.3	-1.4	18			
		40 Nur	60 nber of	80 FReque	100 ests	- 27			

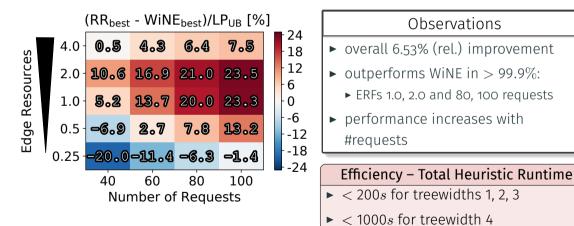
#### Investigate qualitative potential of randomized rounding heuristics.



#### Observations

- ► overall 6.53% (rel.) improvement
- ► outperforms WiNE in > 99.9%:
  - ▶ ERFs 1.0, 2.0 and 80, 100 requests
- performance increases with #requests

#### Investigate qualitative potential of randomized rounding heuristics.



Conclusion

### Thesis Overview and Contributions

Virtual Network Embedding Problem			
Computational Complexity	Problem Relaxations	Offline Approximations	
<ul> <li><i>NP</i>-completeness in various settings</li> <li><i>Structural</i> hardness</li> <li>VMP is <i>NP</i>-complete</li> </ul>	<ul> <li>Valid Mapping Problem</li> <li>DYNVMP Algorithm</li> <li>Fractional VNEP</li> <li>Column Generation LP</li> </ul>	<ul> <li>XP-time approximations</li> <li>under all restrictions</li> <li>profit and cost</li> </ul>	
► even planar requests		Profit VNEP and Evaluation	

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various settings	► DYNVMP Algorithm	► under all restrictions	
<ul> <li>Structural hardness</li> </ul>	► Fractional VNEP	► profit and cost	
► VMP is <i>NP</i> -complete	► Column Generation LP		
<ul> <li>even planar requests</li> </ul>	Heuristics for Offline Profit VNEP and Evaluation		
	► no capacity violations ► can consistently outperform heuristic		

Derived *several* novel theoretic results and showed applicability in practice.

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Specific Embeddings & Embedding Models

#### Virtual Clusters

- *optimal* algorithm for resource minimization
- ► hose-model ~→ bandwidth reduction

#### Temporal VNEP

- incorporation of scheduling aspects
- ► Mixed-Integer Programs to harness flexibility